

# EXAM Introduction to Dynamical Systems

Wednesday January 23, 2019, 10:00 - 13:00 h.

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Write your name and student number on each piece of paper you hand in.

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1. Consider, for  $\varepsilon \in \mathbb{R}$  with  $|\varepsilon|$  sufficiently small and  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  sufficiently smooth with  $f(0, 0) = 0$ , the planar system,

$$\ddot{x} + \varepsilon f(x, \dot{x}) + x - x^3 = 0 \text{ or, equivalently, } \begin{cases} \dot{x} = & y \\ \dot{y} = & -x + x^3 - \varepsilon f(x, y) \end{cases} \quad (1)$$

Note that system (1) has 3 critical points that do not depend on  $\varepsilon$ ,  $(-1, 0)$ ,  $(0, 0)$  and  $(1, 0)$ .

Part **1A**:  $\varepsilon = 0$ .

- 1A(i)**. Determine the integral  $H(x, y)$  of the integrable system (1) (with  $\varepsilon = 0$ ).
- 1A(ii)**. Let  $(x_p(t), y_p(t))$  be the solution of (1) with  $(x_p(0), y_p(0)) = (\frac{1}{2}, 0)$ : determine  $H_p = H(x_p, y_p)$  and show that  $(x_p(t), y_p(t))$  is periodic.
- 1A(iii)**. Give a sketch of the phase portrait of (1) (with  $\varepsilon = 0$ ); indicate explicitly the orbit  $(x_p(t), y_p(t))$  in this sketch.

Part **1B**:  $\varepsilon > 0$ , sufficiently small,  $f(x, y) = y$ .

- 1B(i)**. Show that  $\dot{H}(x, y) \leq 0$  (with  $H(x, y)$  as found in **1A(i)**).
- 1B(ii)**. Now consider the solution  $(x_{\text{fric}}(t), y_{\text{fric}}(t))$  of (1) with (again)  $(x_{\text{fric}}(0), y_{\text{fric}}(0)) = (\frac{1}{2}, 0)$ : show that  $\lim_{t \rightarrow \infty} (x_{\text{fric}}(t), y_{\text{fric}}(t)) = (0, 0)$ ; give a sketch.
- 1B(iii)**. Give a sketch of the basin of attraction  $W^s((0, 0))$  of the (critical) point  $(0, 0)$  in which you clearly indicate its boundary  $\partial W^s((0, 0))$ .
- 1B(iv)**. List all possible omega-limit sets  $\omega(x_0, y_0)$  associated to (1) – where  $(x_0, y_0)$  is the initial condition of the solution  $(x_{\text{fric}}(t), y_{\text{fric}}(t))$  of (1) (with  $\varepsilon > 0$  and  $f(x, y) = y$ ).

Part **1C**:  $f(x, y) = y(H(x, y) - H_p)$ , with  $H(x, y), H_p$  as in **1A(i),(ii)**,  $|\varepsilon|$  sufficiently small.

- 1C(i)**. Show that  $(x_p(t), y_p(t))$  as defined in **1A(ii)** (also) is a periodic solution of (1) if  $\varepsilon \neq 0$ .
- 1C(ii)**. Set  $(x, y) = (x_p(t) + \xi, y_p(t) + \eta)$  and determine the linearized 2-dimensional (time-periodic) system for  $(\xi, \eta)$ .
- 1C(iii)**. Let  $\lambda_1$  and  $\lambda_2$  be the Floquet exponents associated to the linear system determined in **1C(ii)**: note that  $\lambda_1 = 0$  and derive an analytical expression for  $\lambda_2$ . Discuss the stability of  $(x_p(t), y_p(t))$  as function of  $\varepsilon$ .

See Reverse Side

2. Consider for  $g, h : \mathbb{R}^2 \rightarrow \mathbb{R}$  sufficiently smooth the 2-dimensional system,

$$\begin{cases} \dot{x} &= & -x \\ \dot{y} &= & g(x)y + h(x)y^3 \end{cases} \quad (2)$$

Note that  $(0, 0)$  is a critical point of system (2) for all (smooth)  $f(x)$  and  $g(x)$  (and that it is not necessarily the only critical point of (2)).

Part **2A**: the stability of  $(0, 0)$ .

- 2A(i)**. Show that  $(0, 0)$  is stable if  $g(0) < 0$  and unstable if  $g(0) > 0$ .
- 2A(ii)**. Let  $g(0) = 0$ : show that the center manifold  $W^c((0, 0))$  of  $(0, 0)$  is *exactly* given by the  $y$ -axis, i.e. that  $W^c((0, 0)) = \{(x, y) \in \mathbb{R}^2 : x = 0\}$ .
- 2A(iii)**. Let  $g(0) = 0$  and assume  $h(0) \neq 0$ : what can you say about the (asymptotic) stability of  $(0, 0)$ ?
- 2A(iv)**. Let  $g(0) = h(0) = 0$ : what can you say about the (asymptotic) stability of  $(0, 0)$ ? Give a sketch of the flow generated by (2), i.e. its (local) phase portrait, in a neighborhood of  $(0, 0)$ .

Part **2B**:  $g(x) \equiv 0$  – explicit solutions and finite-time blow-up.

- 2B(i)**. Let  $(x(t; (x_0, y_0)), y(t; (x_0, y_0)))$  be the solution of (2) with initial condition  $(x_0, y_0)$ : determine an explicit expression for  $(x(t; (x_0, y_0)), y(t; (x_0, y_0)))$  and show that it is given by,

$$x(t; (x_0, y_0)) = x_0 e^{-t}, \quad y(t; (x_0, y_0)) = \frac{y_0}{\sqrt{1 - 2y_0^2 \int_0^t h(x_0 e^{-s}) ds}}$$

(recall that  $g(x) \equiv 0$ ).

- 2B(ii)**. Assume that  $h(0) > 0$ : show that  $(x(t; (x_0, y_0)), y(t; (x_0, y_0)))$ , or more specifically its  $y$ -component  $y(t; (x_0, y_0))$ , necessarily blows up in finite time.
- 2B(iii)**. Assume that  $h(0) < 0$ : show that  $\lim_{t \rightarrow \infty} (x(t; (x_0, y_0)), y(t; (x_0, y_0))) = (0, 0)$  for  $|x_0|$  sufficiently small.
- 2B(iv)**. Let  $h(0) = 0$  and define,

$$\mathcal{H}_\infty(x_0) = \int_0^\infty h(x_0 e^{-s}) ds.$$

Note that solutions  $(x(t; (x_0, y_0)), y(t; (x_0, y_0)))$  must again blow up in finite time if  $1 - 2y_0^2 \mathcal{H}_\infty(x_0) < 0$  (by an argument similar to that of **2B(ii)**). Can solutions blow up in finite time if  $1 - 2y_0^2 \mathcal{H}_\infty(x_0) > 0$ ?

- 2B(v)**. Keep  $h(0) = 0$ : show that solutions  $(x(t; (x_0, y_0)), y(t; (x_0, y_0)))$  exist for all  $t \geq 0$  if  $x_0$  is sufficiently small.
- 2B(vi)**. Continue with  $h(0) = 0$  and assume that  $\mathcal{H}_\infty(x_0) > 0$ : determine the limit behavior  $\lim_{t \rightarrow \infty} (x(t; (x_0, y_0)), y(t; (x_0, y_0)))$  as function of  $(x_0, y_0)$ . Give a sketch of the phase portrait.